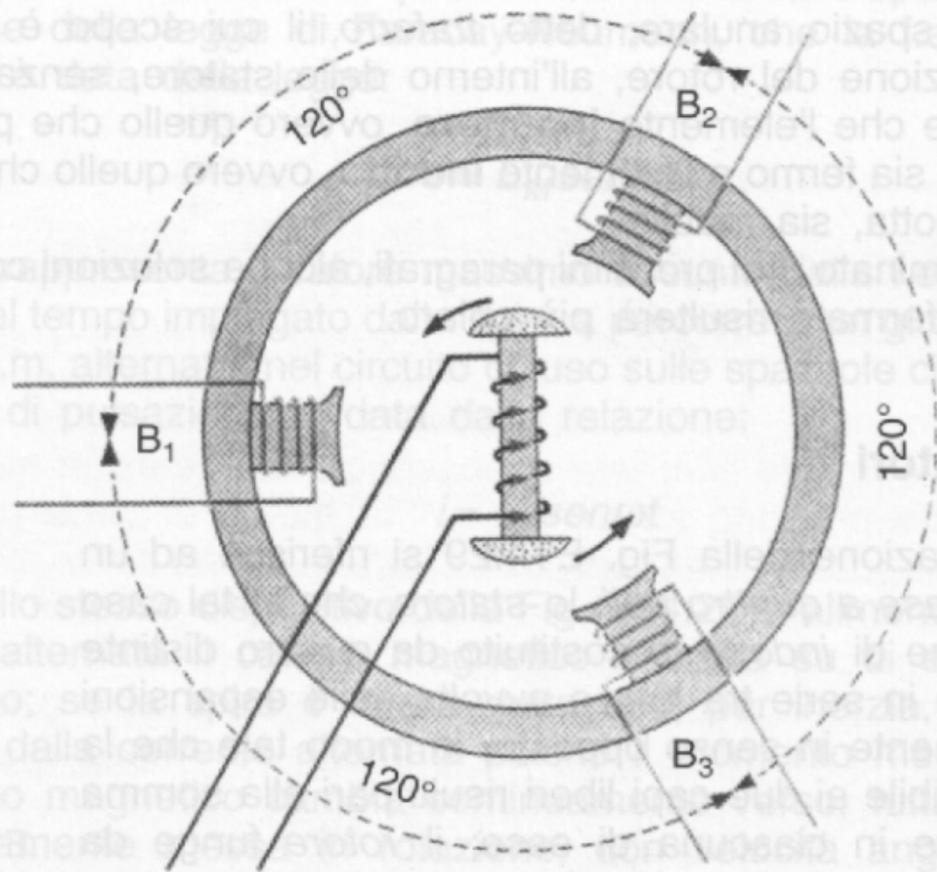


Fig. ET4.29 - Alternatore monofase a quattro poli.



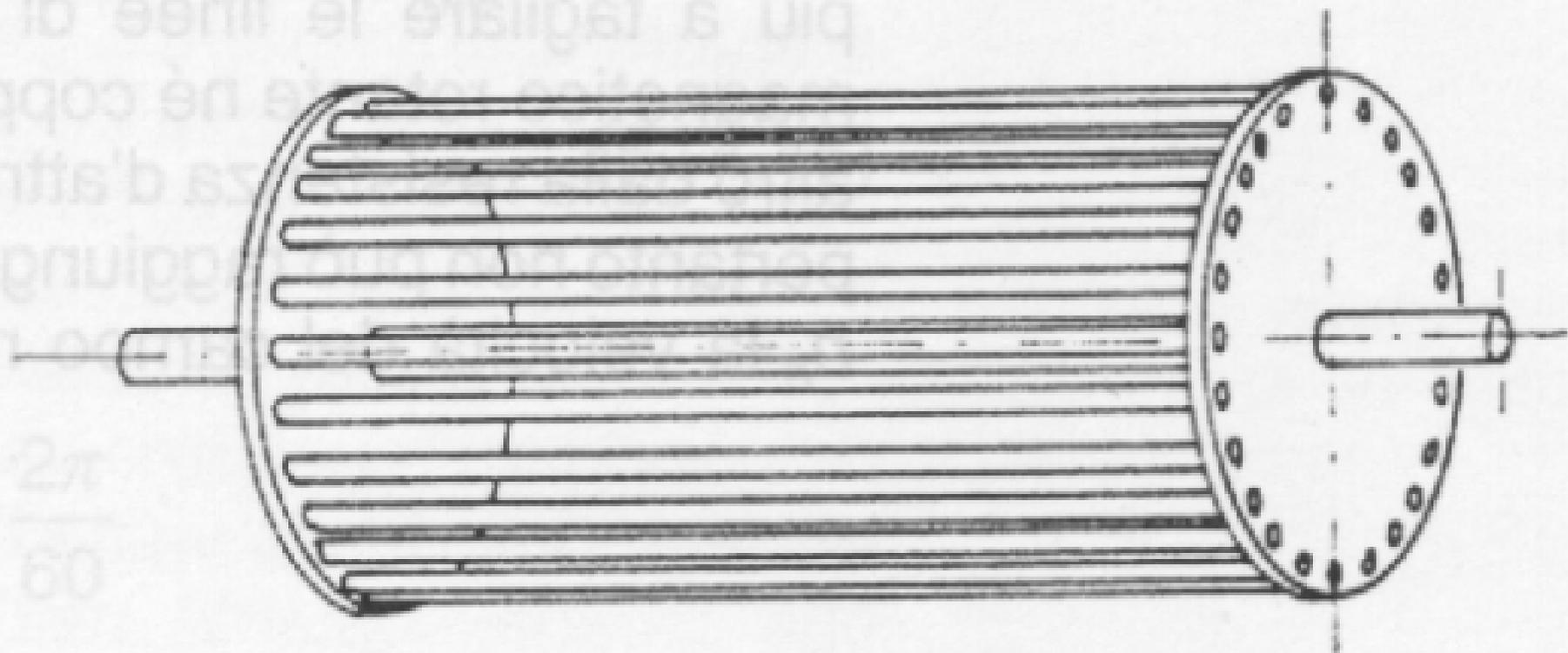
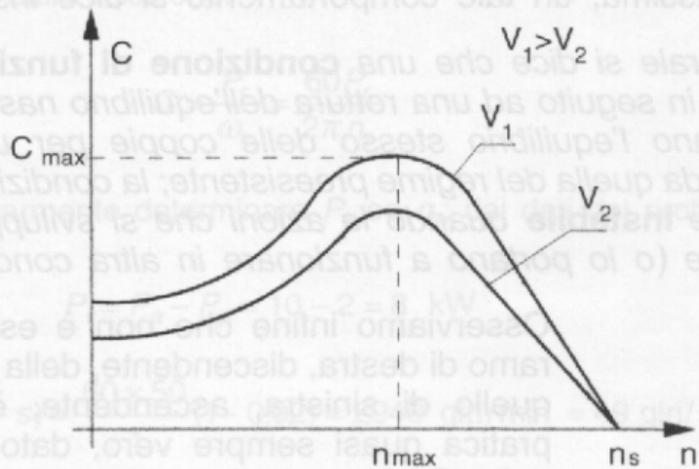
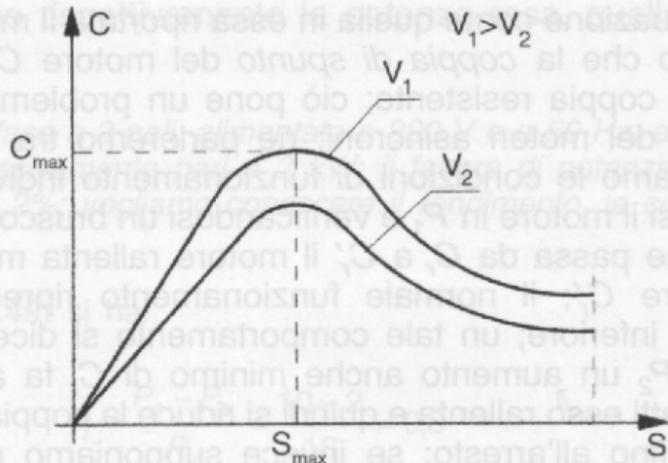


Fig. ET4.31 - Rotore a gabbia di scoiattolo.



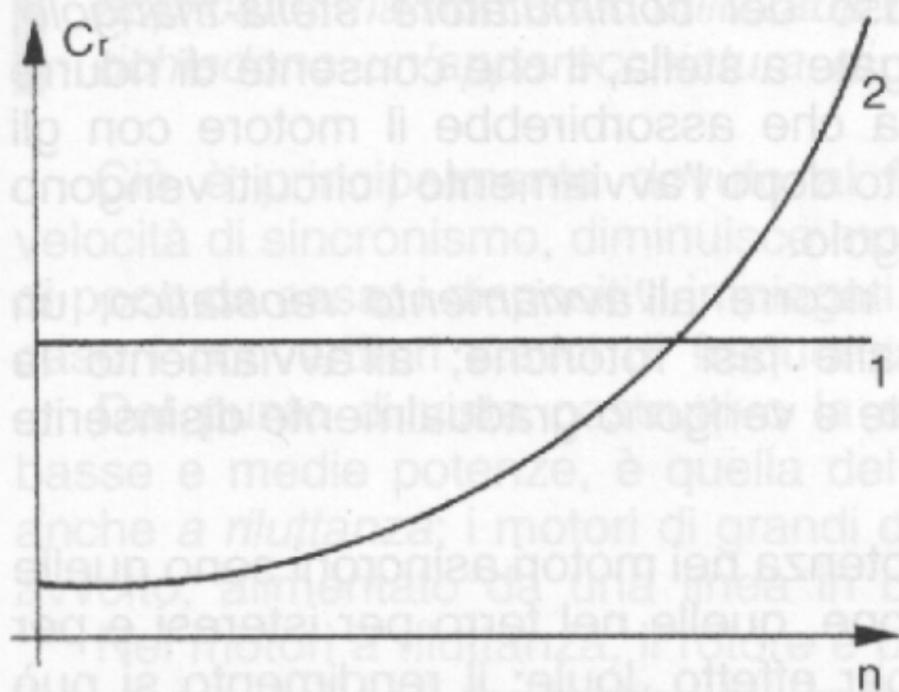


Fig. ET4.34 - Possibili andamenti della coppia resistente; (1) montacarichi, (2) pompa centrifuga.

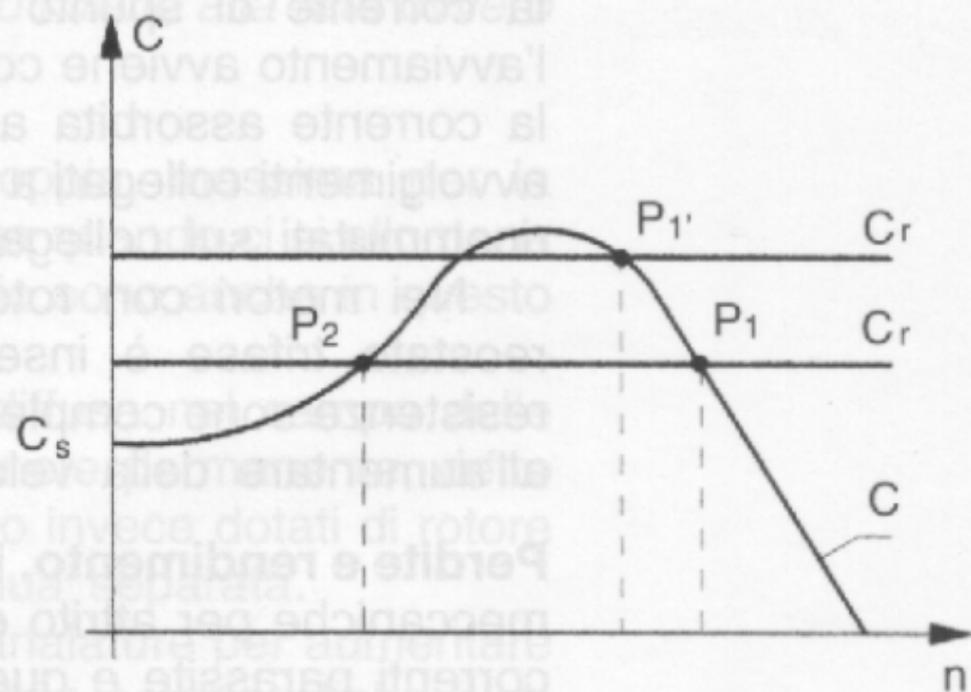
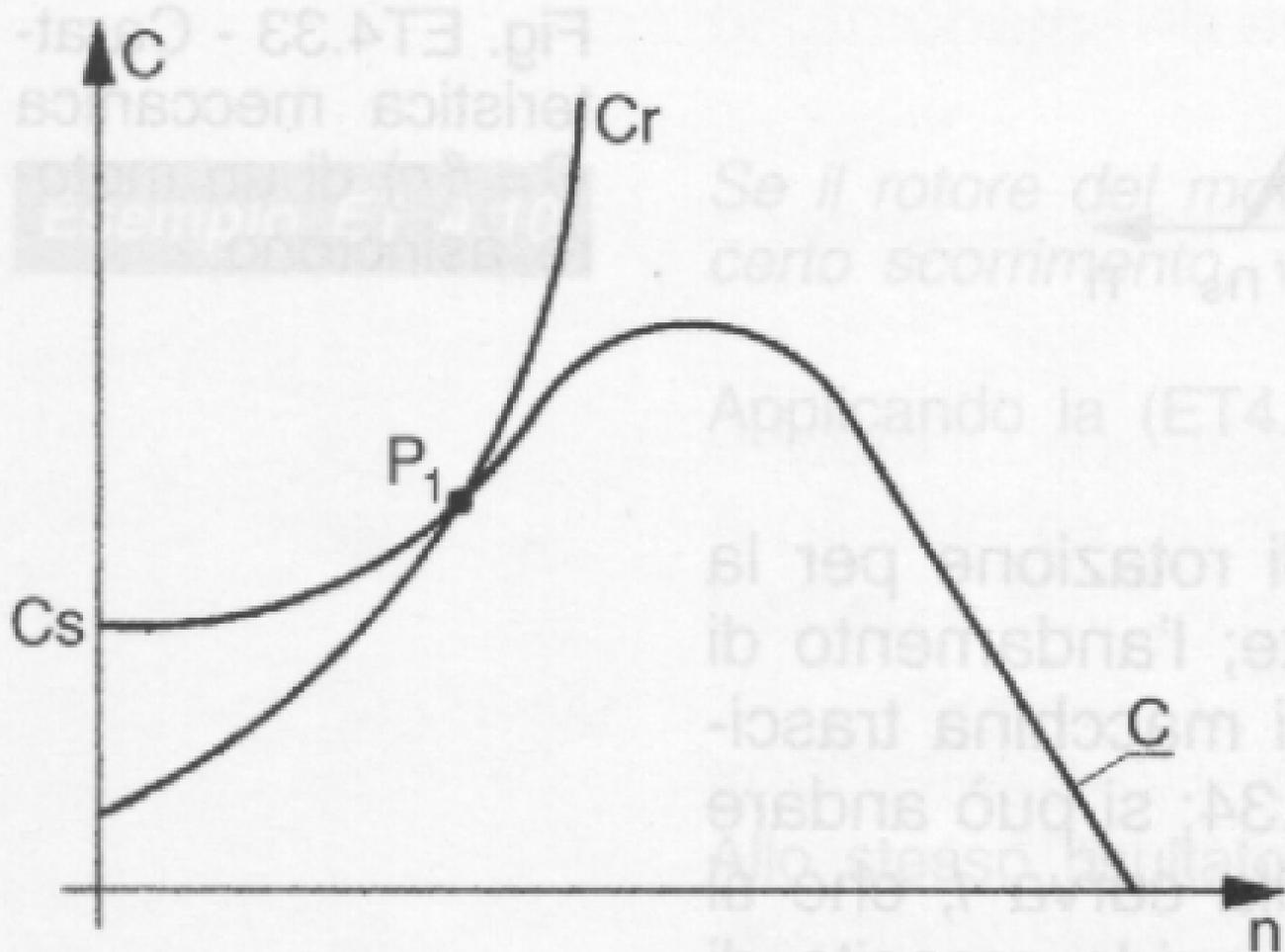
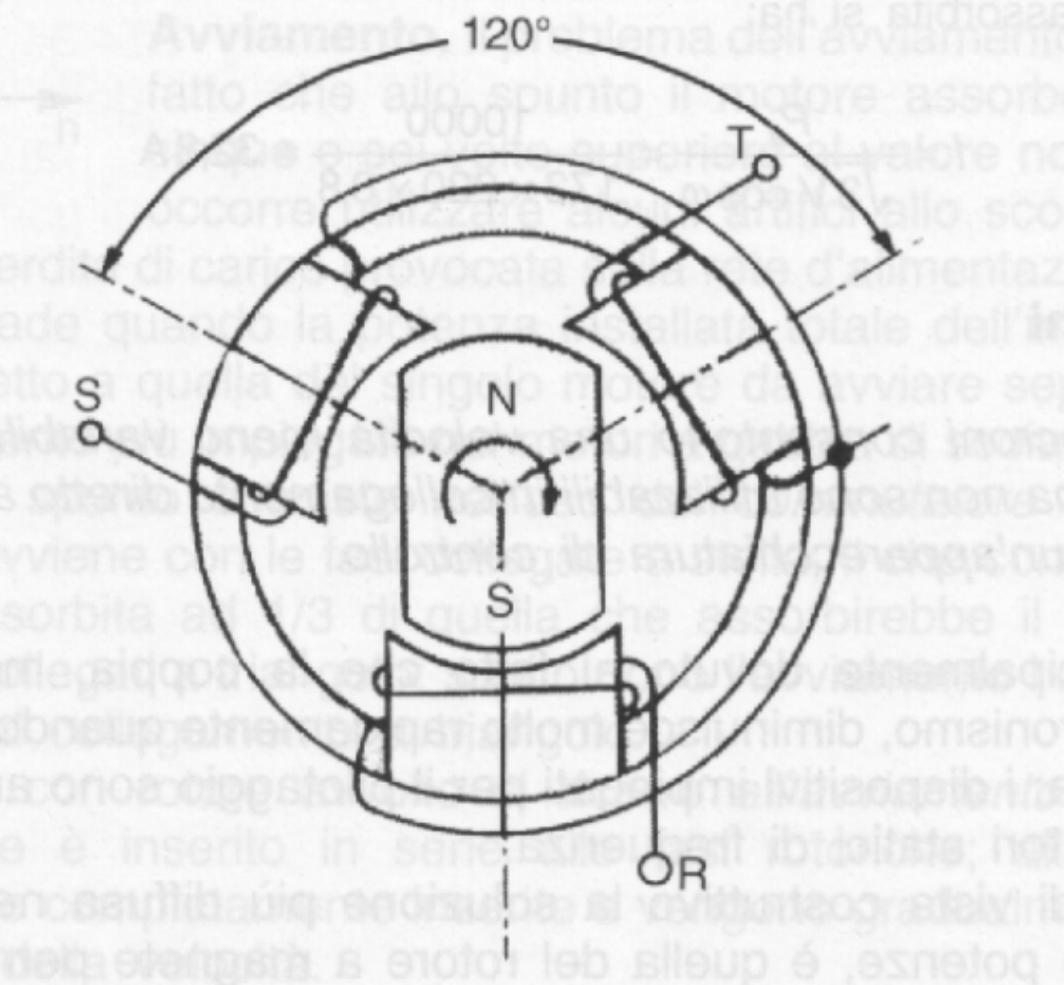
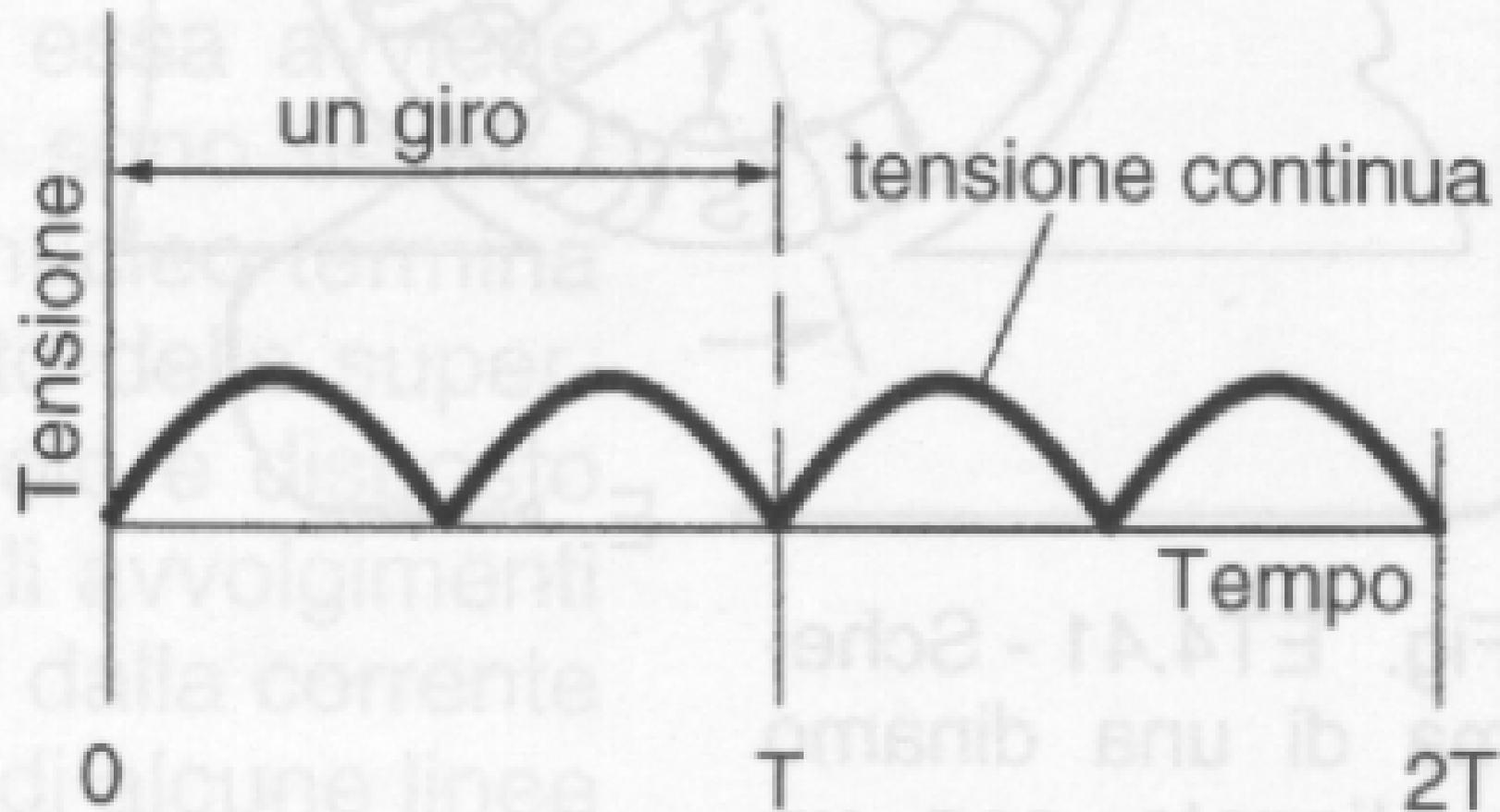
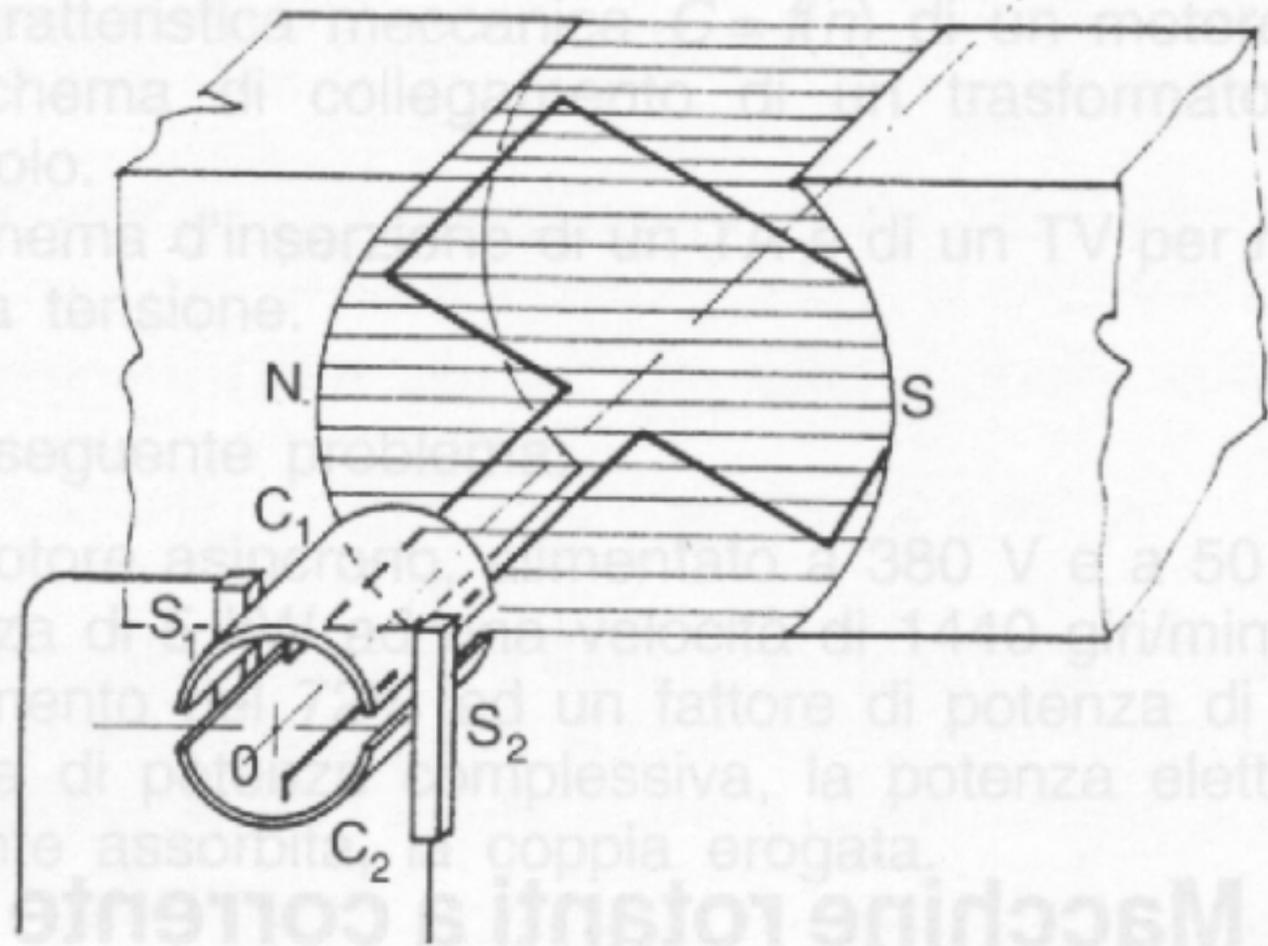


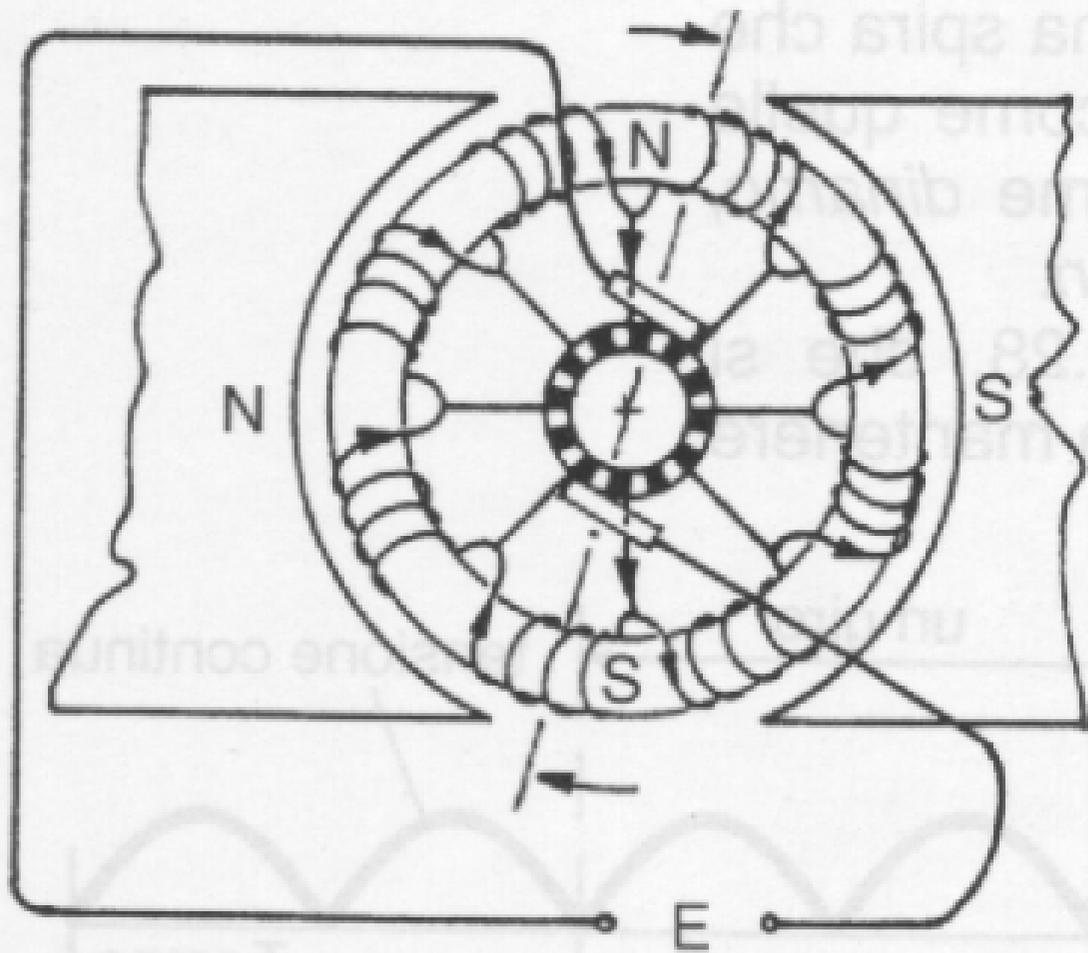
Fig. ET4.35 - Confronto tra C e C_r

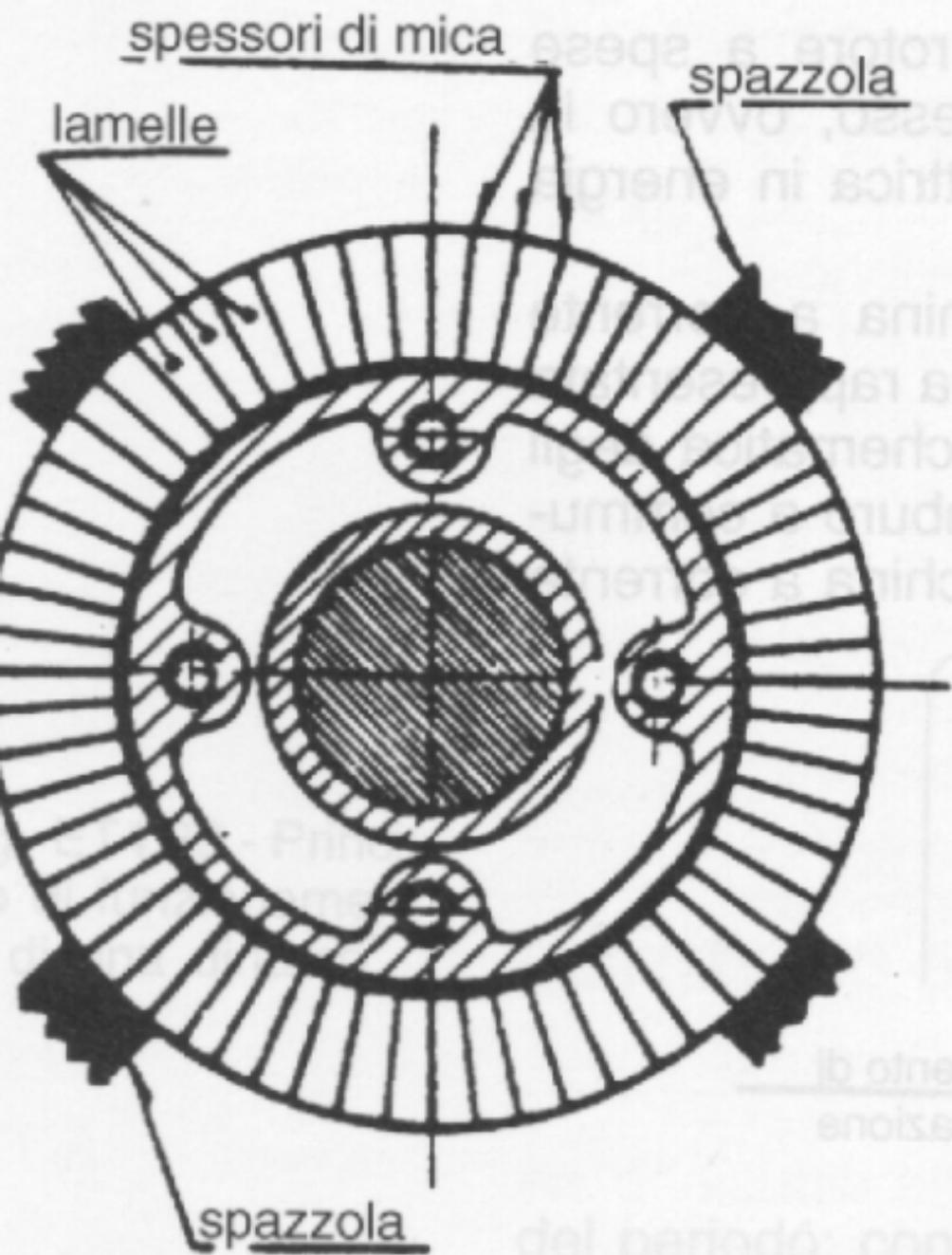


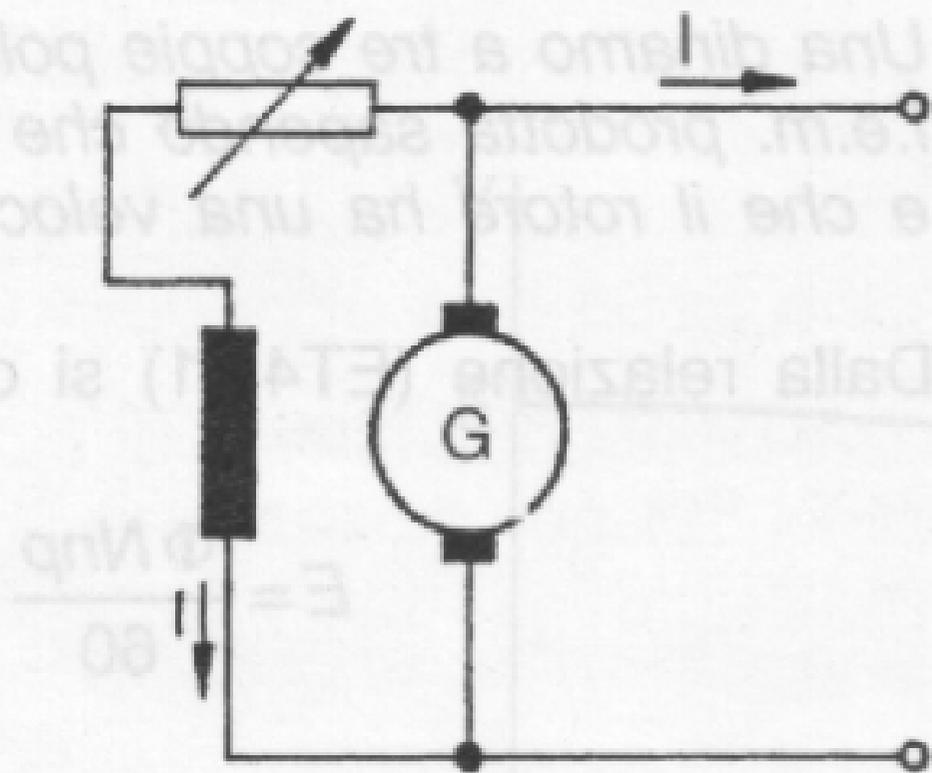
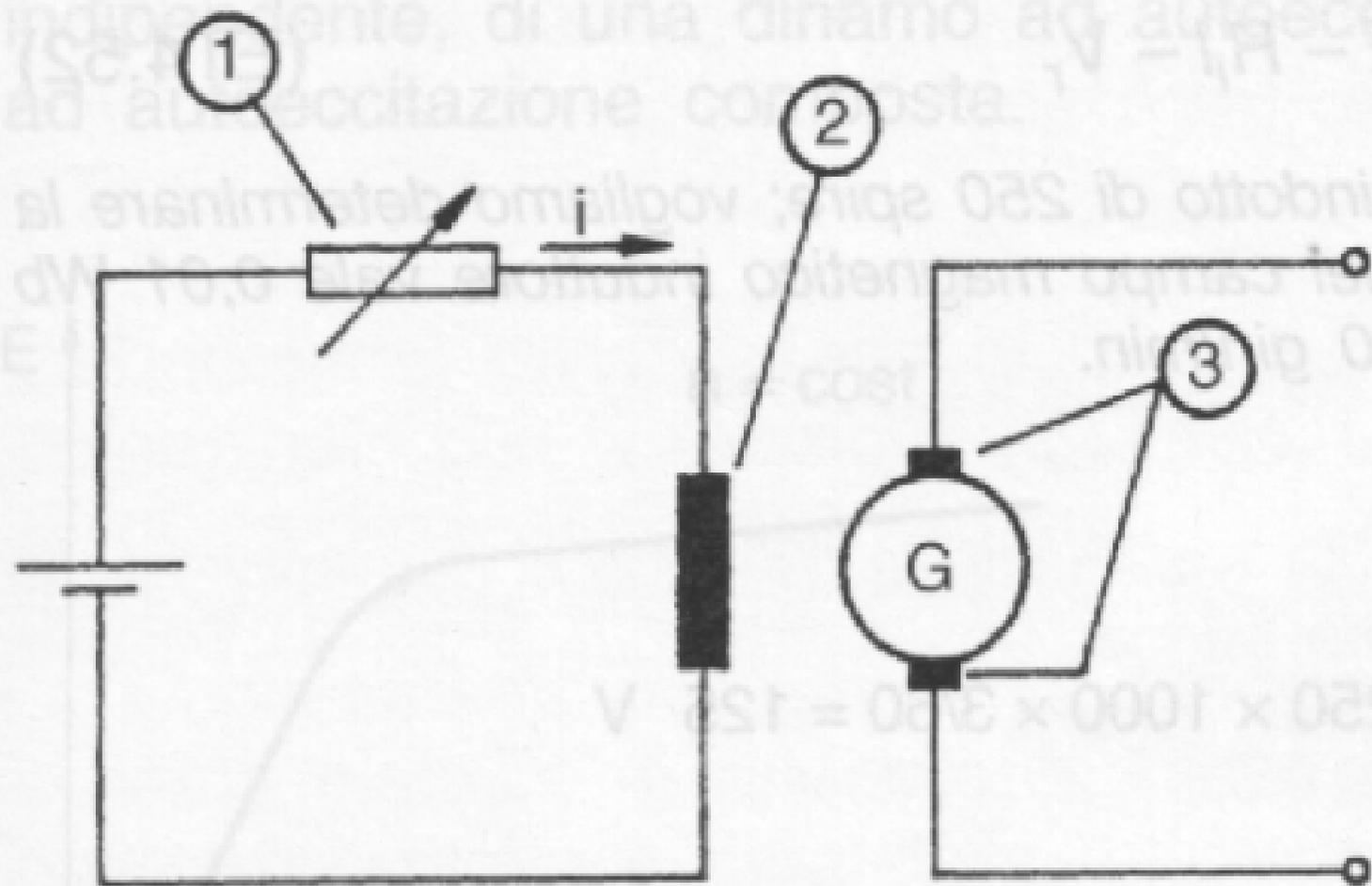


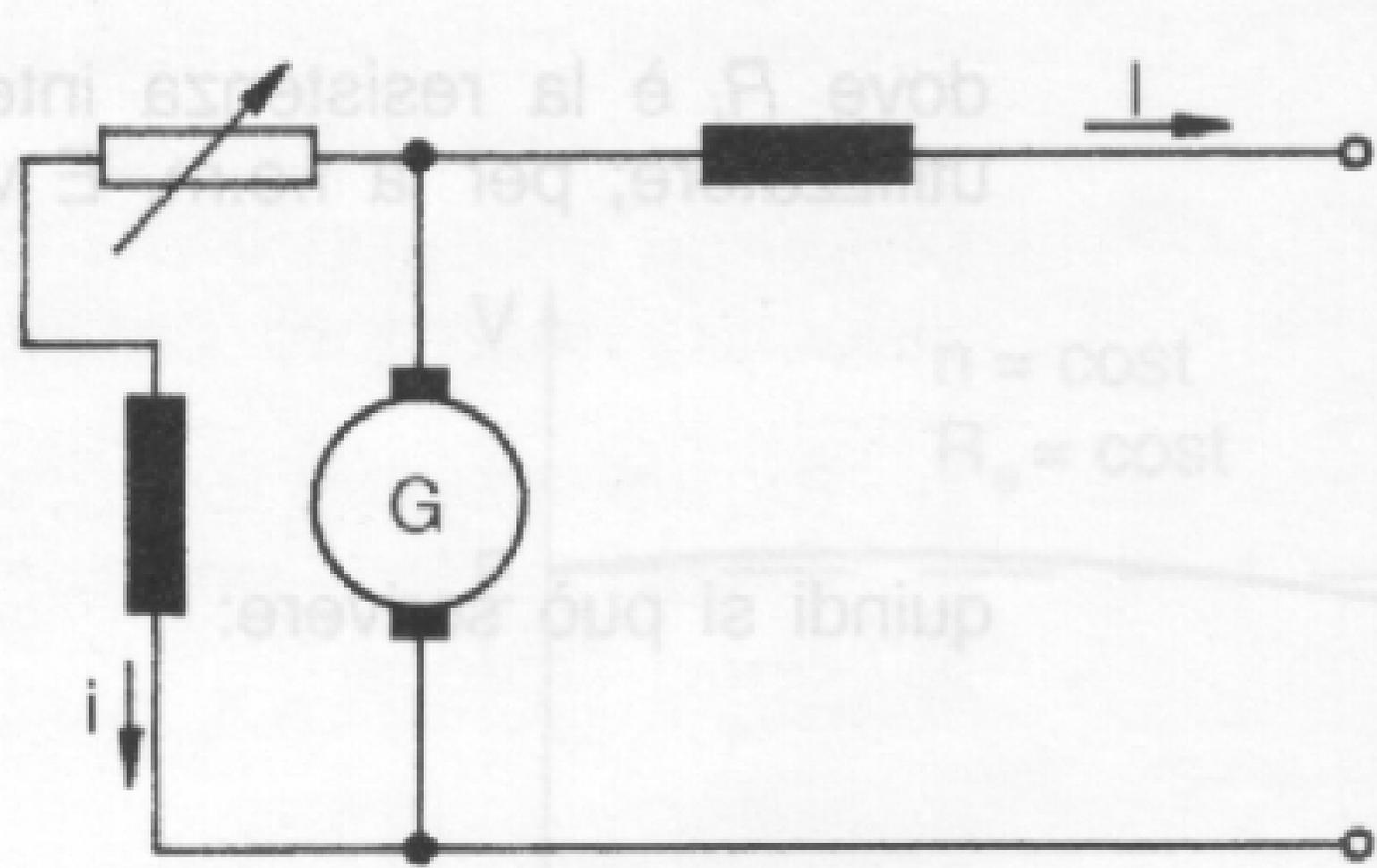
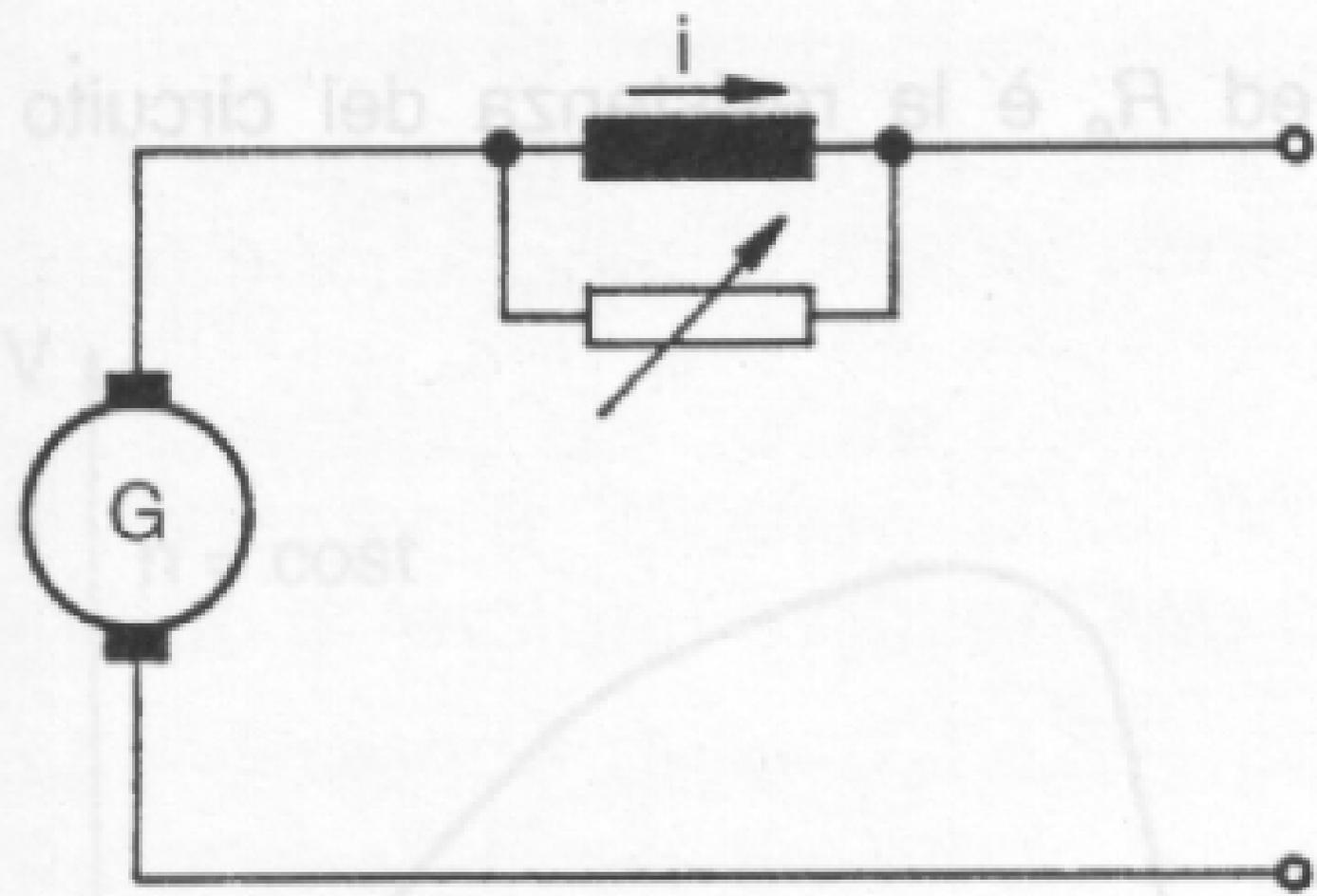












$$I = \frac{\Phi N n p}{(R_l + R_g) 60}$$

$$E = \frac{\Phi N n p}{60}$$

$$R_g = \text{cost}$$

$$\eta = \text{cost}$$

dove R_g è la resistenza interna della dinamo ed R_l è la resistenza del circuito
 induttore, per la quale vale la relazione:

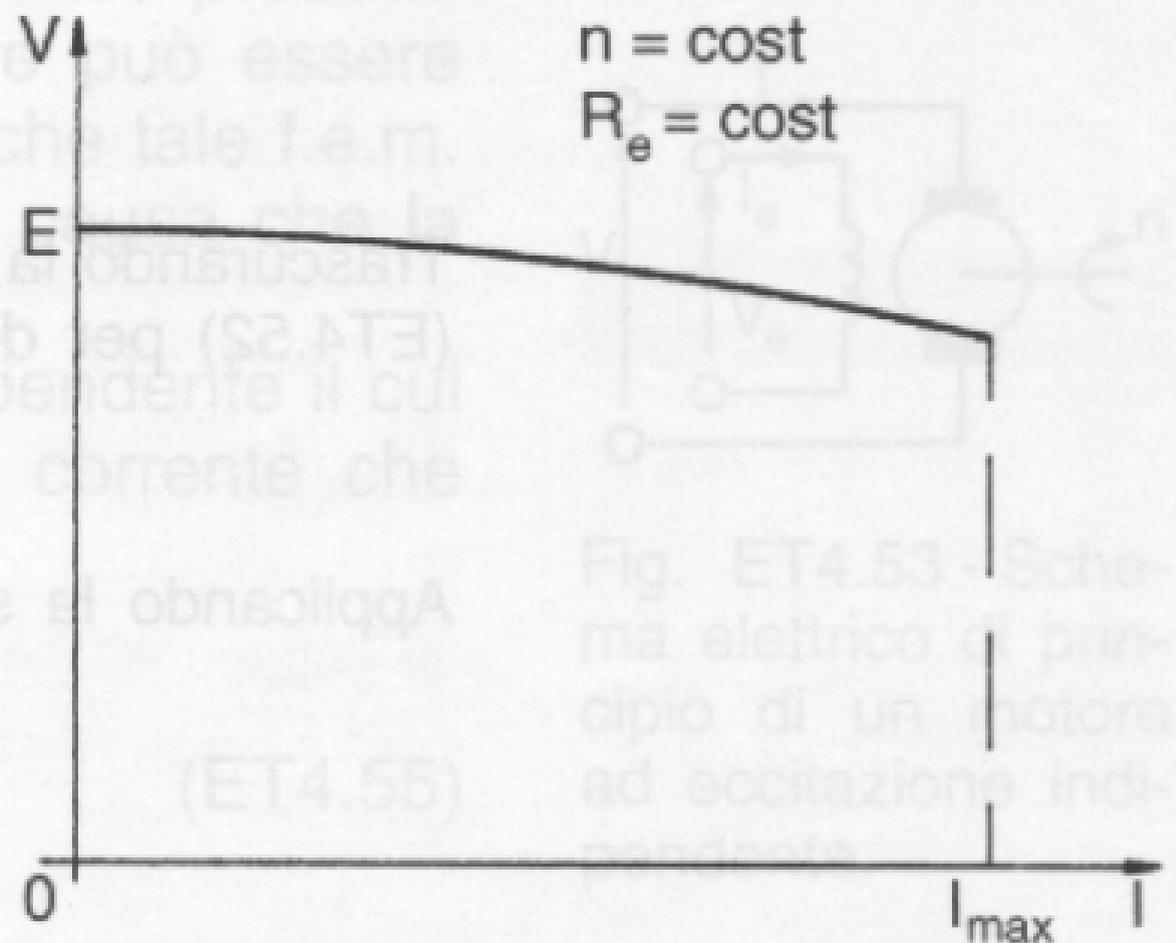
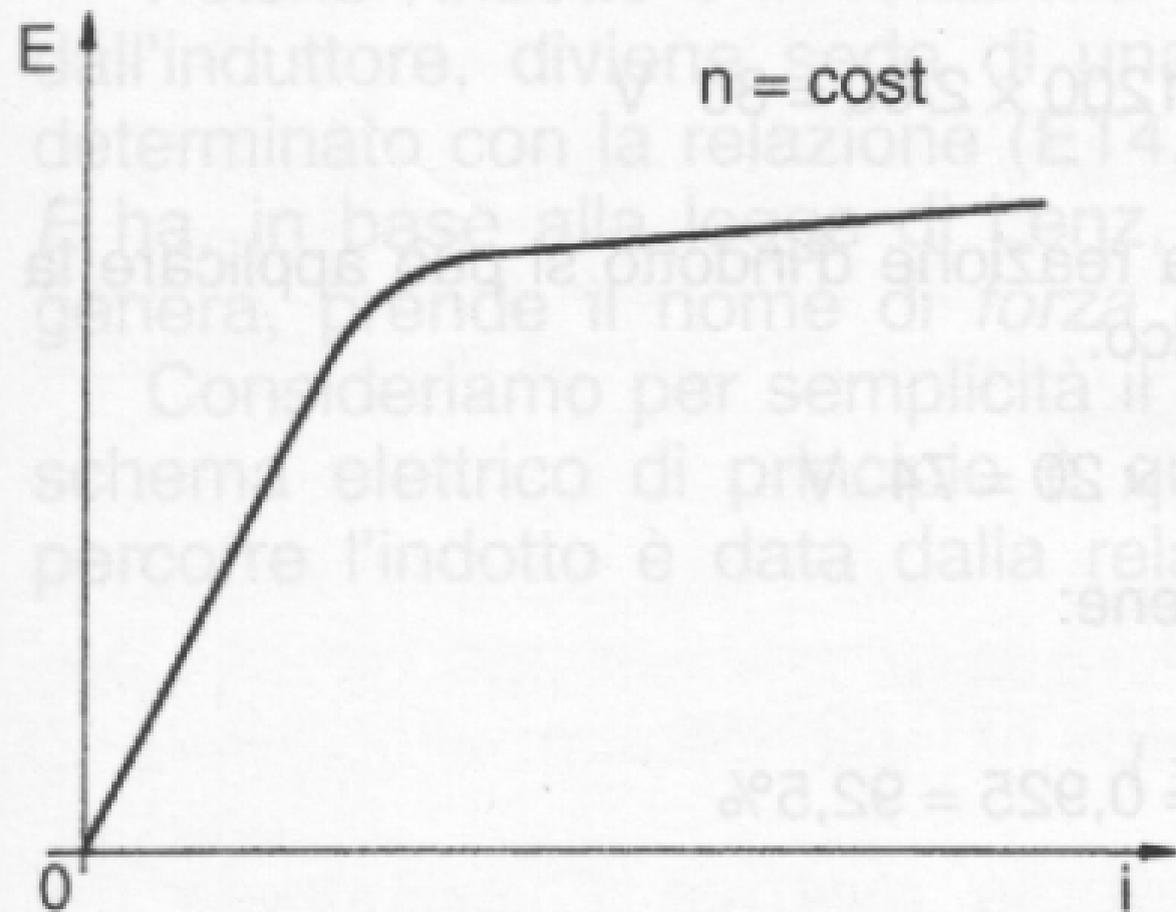


Fig. ET4.53 Schema elettrico di principio di un motore ad eccitazione indipendente.

$$\eta_e = \frac{V \cdot I - V_e \cdot I}{V \cdot I} = \frac{V - V_e}{V} = \frac{V - E}{V} = \frac{V - E}{E + I R_e} \quad (\text{ET4.55})$$

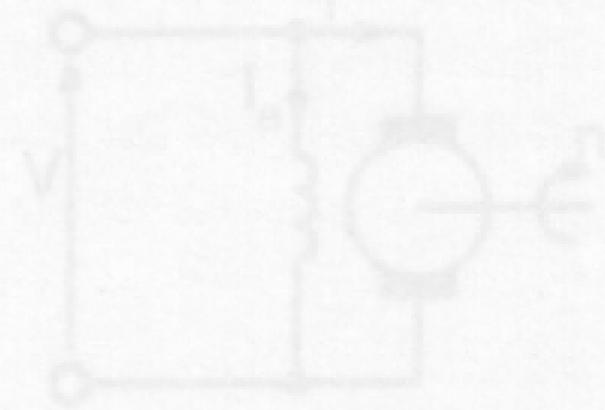
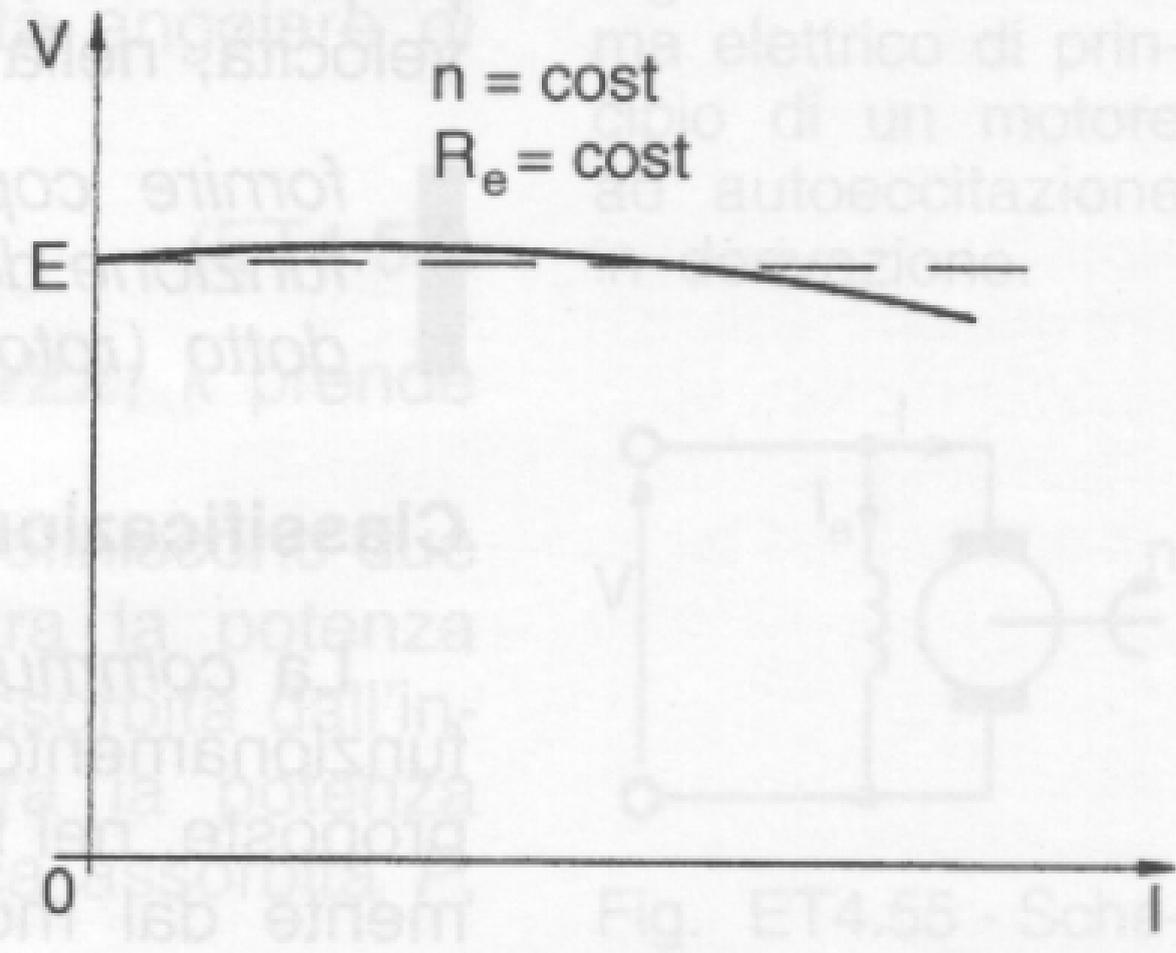
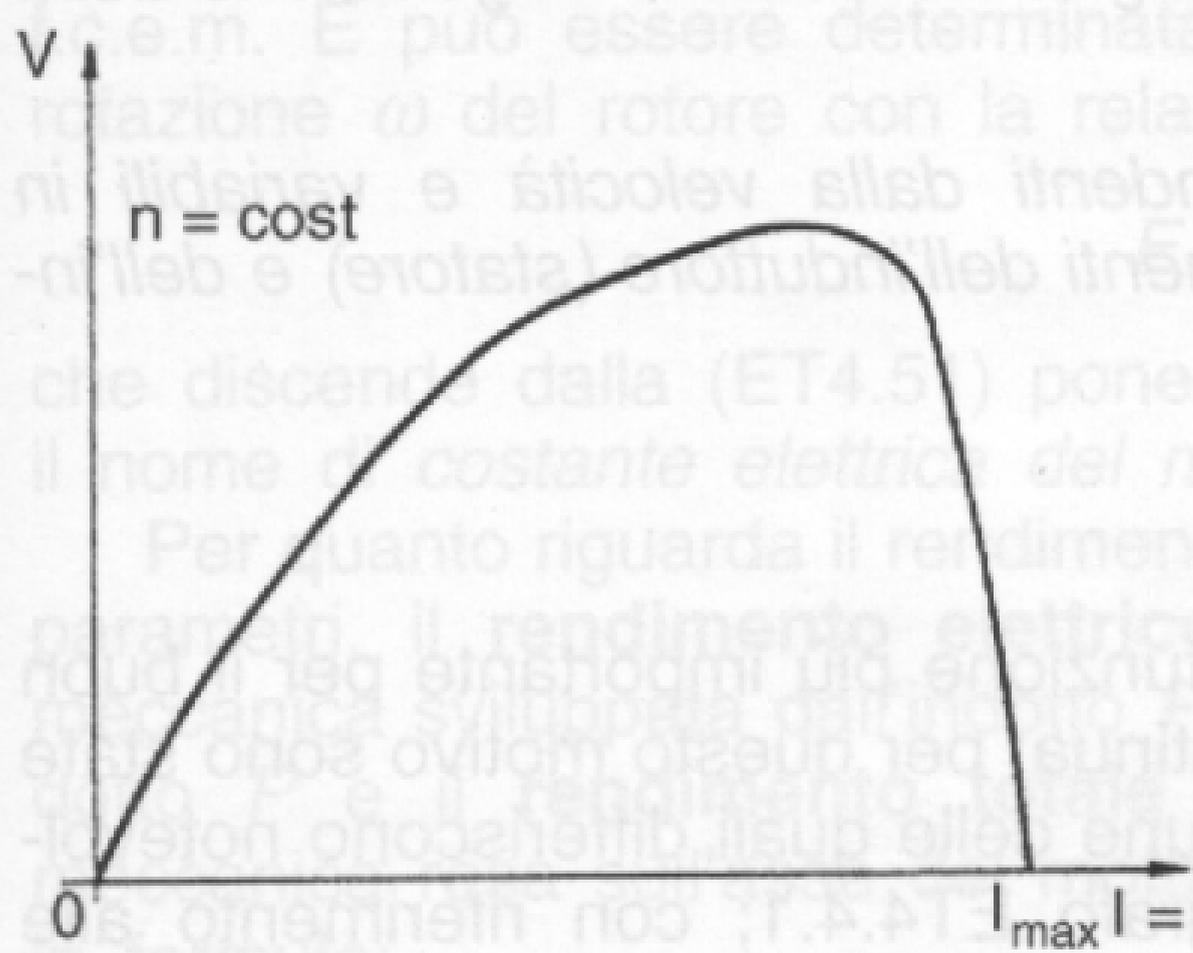


Fig. ET4.55 - Sch 1

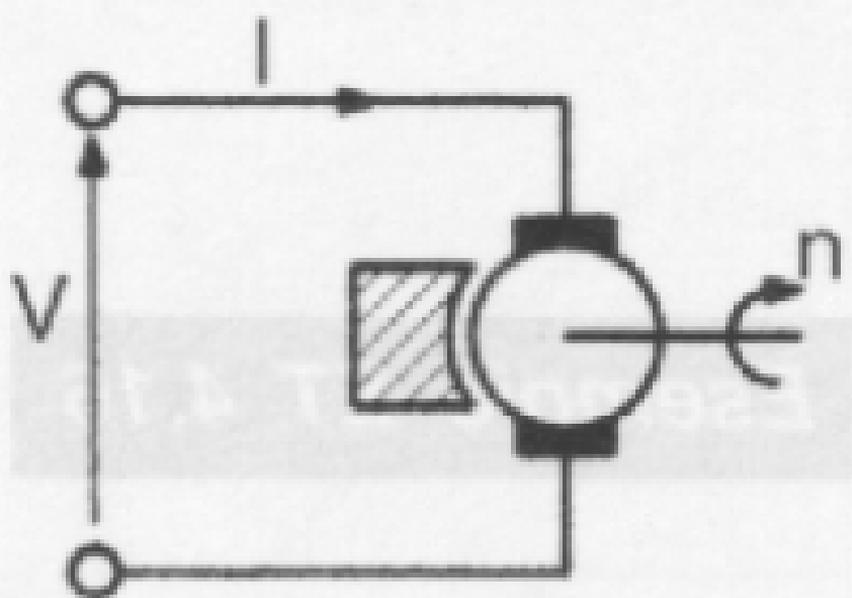


Fig. ET4.52 - Schema elettrico di principio di un motore ad eccitazione a magnete permanente.

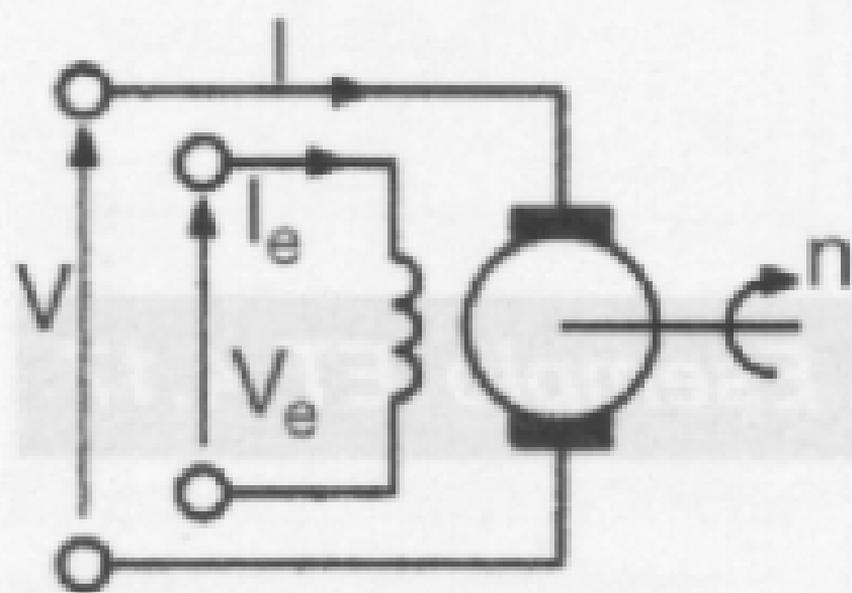


Fig. ET4.53 - Schema elettrico di principio di un motore ad eccitazione indipendente.

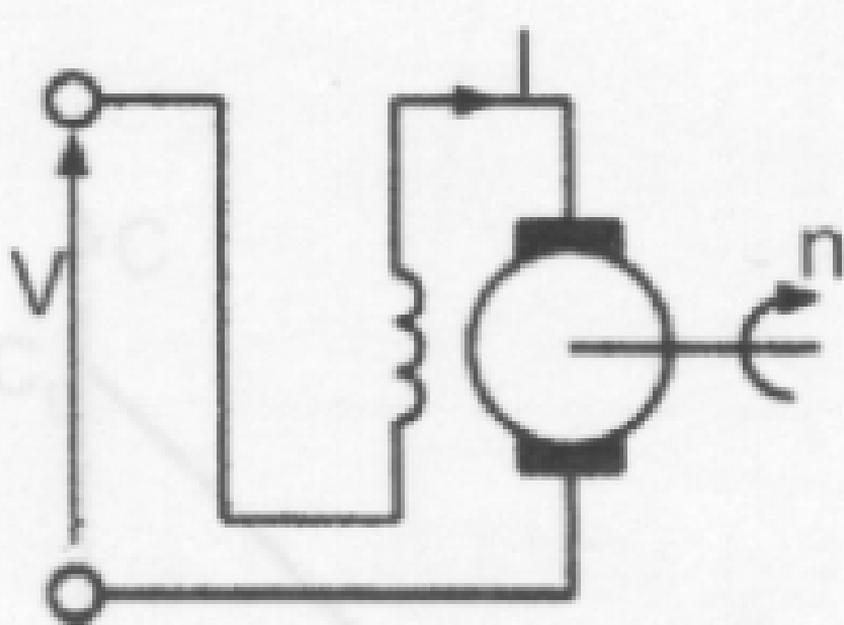


Fig. ET4.54 - Schema elettrico di principio di un motore ad autoeccitazione in derivazione.

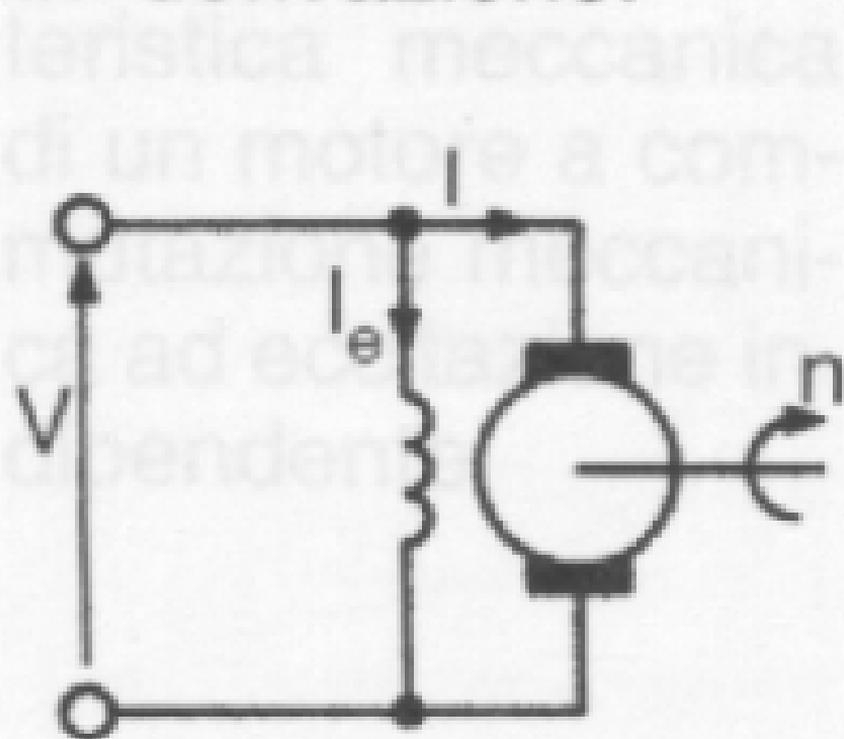
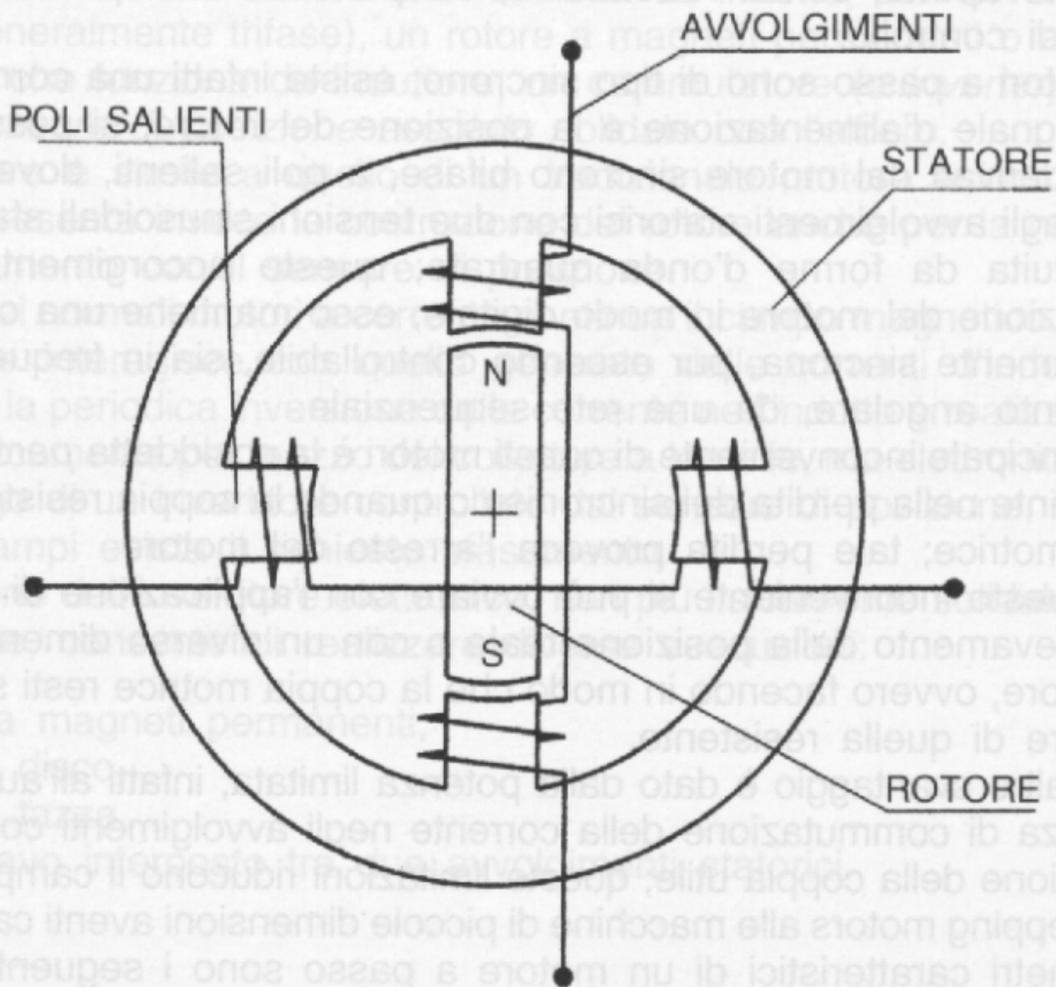


Fig. ET4.55 - Schema elettrico di principio di un motore ad autoeccitazione in serie.



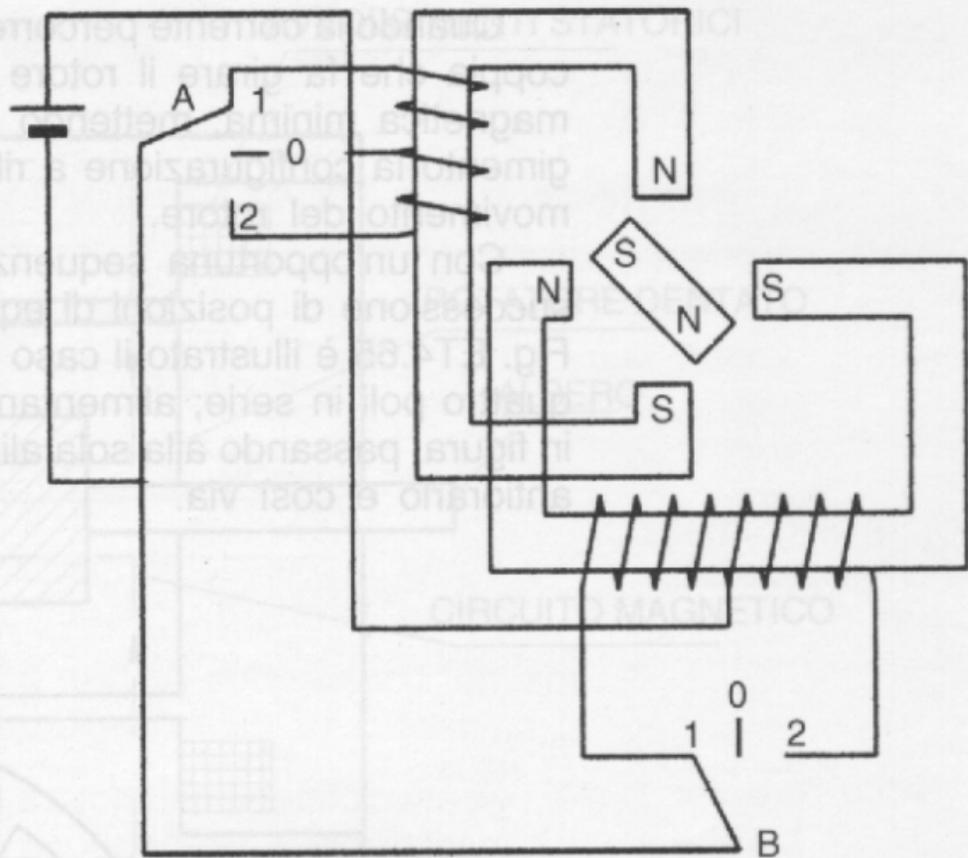


Fig. ET4.63

